



Piero Alberini Trophy - Italian - British Championship OPEN 2025

📅 Aug 9 - Aug 16, 2025 🇮🇹 Villa Scirca, Sigillo, ITA



Category 2
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Task4 Overall

2025-08-14

Task info

🔔 Task is set 70.957 km. Start at 13:15. Task deadline at 18:00.

📍 [Live tracking](#)

Updated Sep 1, 2025 14:00

#	Id	Name	Nat	Glider	Sponsor	SS	ES	Time [h:m:s]	Speed [km/h]	Distance [km]	Dist. Points	Lead. Points	Time Points	Arr. Pos. Points	Total	
1	85	TIM KING	M	GBR	A-1-R Atos Vq	Kings of Hampshire Ltd BHPA	13:15:00	4T15:50	02:35:09	26.31	71.0	549.3	37.8	151.4	27.0	765.6
2	80	MARZIO DIGIUSTO	M	ITA	A-1-R Atos Vr	AeCI	13:15:00				56.6	493.9	36.2			530.1
3	76	JINDRICH KRAL	M	CZE	A-1-R Atos Vr+	LAA	13:15:00				54.7	481.8	29.0			510.8
4	81	MIKE ARMSTRONG	M	GBR	A-1-R Atos Vq	British Hang Gliding & Paragliding Association	13:15:00				55.8	489.3	20.3			509.6
5	83	NEIL ATKINSON	M	GBR	A-1-R Atos Vr	Avon	13:15:00				51.0	450.8	22.0			472.8
6	77	JOCHEN ZEYHER	M	GER	A-1-R Atos Vr	Chiba Thermopad	13:15:00				23.1	181.5	5.5			186.9
7	47	NEITHARD MÜLLER	M	GER	A-1-R Atos Vr		13:15:00				18.0	150.3				150.3
8	74	HAMISH ATKINSON	M	GBR	A-1-R Atos Vr		13:15:00				16.5	140.3				140.3
ABS	75	IAN MACADAM	M	GBR	Wills Wing U2											0.0
ABS	78	JUN TOMIHARA	M	JPN	A-1-R Atos Vr											0.0
ABS	84	PHIL SOUTHWARD	M	NZL	A-1-R Atos Vr											0.0

Task definition

No	Leg	Dist.	Id	Radius	Open	Close	Coordinates	Altitude
1	0.0	km	1CN112	0 m	12:15	15:00	Lat: 43.35648, Lon: 12.7716	1118 m
2SS	2327.1	km	BRA039	14000 m	13:15	18:00	Lat: 43.27055, Lon: 12.68862	394 m
3	6602.8	km	CAV035	1000 m	13:15	18:00	Lat: 43.40972, Lon: 12.82445	350 m
4	27627.0	km	NER150	8000 m	13:15	18:00	Lat: 43.5581, Lon: 12.51947	1504 m
5	43150.6	km	VEN054	1000 m	13:15	18:00	Lat: 43.47445, Lon: 12.7925	540 m
6	56324.5	km	9LV042	1000 m	13:15	18:00	Lat: 43.34778, Lon: 12.81722	420 m
7	63865.1	km	BAR042	1000 m	13:15	18:00	Lat: 43.30707, Lon: 12.72317	420 m
8	69075.8	km	CLD055	3000 m	13:15	18:00	Lat: 43.38305, Lon: 12.68695	550 m
9ES	70357.4	km	5LS048	1000 m	13:15	18:00	Lat: 43.34445, Lon: 12.72445	476 m
10	70957.4	km	5LS048	400 m	13:15	18:00	Lat: 43.34445, Lon: 12.72445	476 m

Penalties

Id	Name	Penalty %	Penalty Points	Penalty Reason
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Task statistics

param	value
ss_distance	68.03
task_distance	70.957
launch_to_ess_distance	70.357
no_of_pilots_present	8
no_of_pilots_flying	8
no_of_pilots_lo	7
no_of_pilots_reaching_nom_dist	0
no_of_pilots_reaching_es	1
no_of_pilots_reaching_goal	1
sum_flown_distance	346.618
best_dist	70.957
best_time	2.585833333333333
worst_time	2.585833333333333
no_of_pilots_in_competition	11
no_of_pilots_landed_before_stop	0
sum_dist_over_min	290.618
sum_real_dist_over_min	290.618
best_real_dist	70.957
last_start_time	2025-08-14T13:15:00+02:00
first_start_time	2025-08-14T13:15:26+02:00
first_finish_time	2025-08-14T15:50:09+02:00
max_time_to_get_time_points	0.0
no_of_pilots_with_time_points	1
goalratio	0.125
arrival_weight	0.035
departure_weight	0
leading_weight	0.049
time_weight	0.198
distance_weight	0.717
smallest_leading_coefficient	1.72814970938955
available_points_distance	549.307227702627
available_points_time	151.39880752405352
available_points_departure	0
available_points_leading	37.84970188101338
available_points_arrival	27.03550134358099
time_validity	1.0
launch_validity	1.0
distance_validity	0.766
stop_validity	1.0
day_quality	0.766
ftv_day_validity	0.7655912384512749
time_points_stop_correction	0

Scoring formula settings

param	value
id	GAP2025
min_dist	7
nom_dist	80
nom_time	1.5
nom_launch	0.96
nom_goal	0.3
day_quality_override	0
bonus_gr	5
jump_the_gun_factor	2.0
jump_the_gun_max	300
normalize_1000_before_day_quality	0
time_points_if_not_in_goal	0.8
use_1000_points_for_max_day_quality	0
use_arrival_position_points	1
use_arrival_time_points	0
use_departure_points	0
use_difficulty_for_distance_points	1
use_distance_points	1
use_distance_squared_for_IC	0
use_leading_points	1
use_semi_circle_control_zone_for_goal_line	1
use_time_points	1
scoring_altitude	QNH
final_glide_decelerator	none
no_final_glide_decelerator_reason	
min_time_span_for_valid_task	0
score_back_time	15
use_proportional_leading_weight_if_nobody_in_goal	
leading_weight_factor	0.175
turnpoint_radius_tolerance	0.001
use_arrival_altitude_points	0

Sponsors



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