



XXXVIII Valerio Albrizio Trophy 2026

📅 Apr 24 - Apr 26, 2026

🇮🇹 Laveno Mombello, ITA



Category 2
HG CLASS 1
HG CLASS 1 SPORT

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RESULTS

REGISTRATION

HG CLASS 1

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Task2 Overall

2026-04-25

Task info

🕒 Task is set 41.043 km. Start at 15:00. Task deadline at 18:30.

📍 Live tracking

Updated Apr 27, 2026 07:49

#	Id	Name	Nat	Glider	Sponsor	SS	ES	Time [h:m:s]	Speed [km/h]	Distance [km]	Dist. Points	Lead. Points	Time Points	Arr. Pos. Points	Total		
1	773	GARY WIRDNAM	M	GBR	Icaro2000 Alto			15:00:00	5T16:30:	01:30:43	25.08	41.0	322.1	17.6	70.3	12.6	422.5
2	772	FEDERICO ROMANI	M	ITA	Icaro2000 Mastr			15:00:00			33.3	291.8	3.8				295.6
3	777	PAWEL WIERZBOWSKI	M	AUT	Vega Mx	Sonnenhof Kadolz		15:00:00			21.4	221.9	3.6				225.4
4	771	CESARE CRISTOFORONI	M	ITA	Icaro2000 Mastr			15:00:00			7.9	144.8					144.8
5	758	GERD LAUBENTHAL	M	SUI	Designproducts She			15:00:00			7.6	142.9					142.9
6	778	PHILIPP REICHEGGER	M	ITA	Wills Wing Sport 3			15:00:00			7.5	142.1					142.1
7	774	MANUEL BALDIN	M	ITA	Wills Wing U2			15:00:00			7.5	142.0					142.0
8	775	MARIAN KOMAN	M	POL	Wills Wing Sport 3			15:00:00			7.0	136.9					136.9
8	776	MARIO SANSEVERINO	M	ITA	Icaro2000 Alto L	Sanseverinocostruzioni		15:00:00			7.0	136.9					136.9
8	779	SEBASTIAN DALMAU	M	ECU	Icaro2000 Orbiter-2	Bodeguitas Express		15:00:00			7.0	136.9					136.9
8	780	SERGE MAINENTE	M	FRA	Wills Wing Sport 3	MyWife- Tahiti Delta Club		15:00:00			7.0	136.9					136.9

Task definition

No	Leg	Dist.	Id	Radius	Open	Close	Coordinates	Altitude
1	0.0 km		3NU111	0 m	14:00	14:30	Lat: 45.92225, Lon: 8.67407	1110 m
2SS	2525.5 km		SMA109	3000 m	15:00	16:00	Lat: 45.92693, Lon: 8.74498	1090 m
3	5134.5 km		SMA109	400 m	15:00	18:30	Lat: 45.92693, Lon: 8.74498	1090 m
4	13441.3 km		PIC053	400 m	15:00	18:30	Lat: 45.88601, Lon: 8.64346	530 m
5	27464.4 km		STE097	1000 m	15:00	18:30	Lat: 45.97143, Lon: 8.80014	970 m
6ES	40442.7 km		1AT030	1000 m	15:00	18:30	Lat: 45.89688, Lon: 8.63927	300 m
7	41042.8 km		1AT030	400 m	15:00	18:30	Lat: 45.89688, Lon: 8.63927	300 m

Penalties

id	Name	Penalty %	Penalty Points	Penalty Reason
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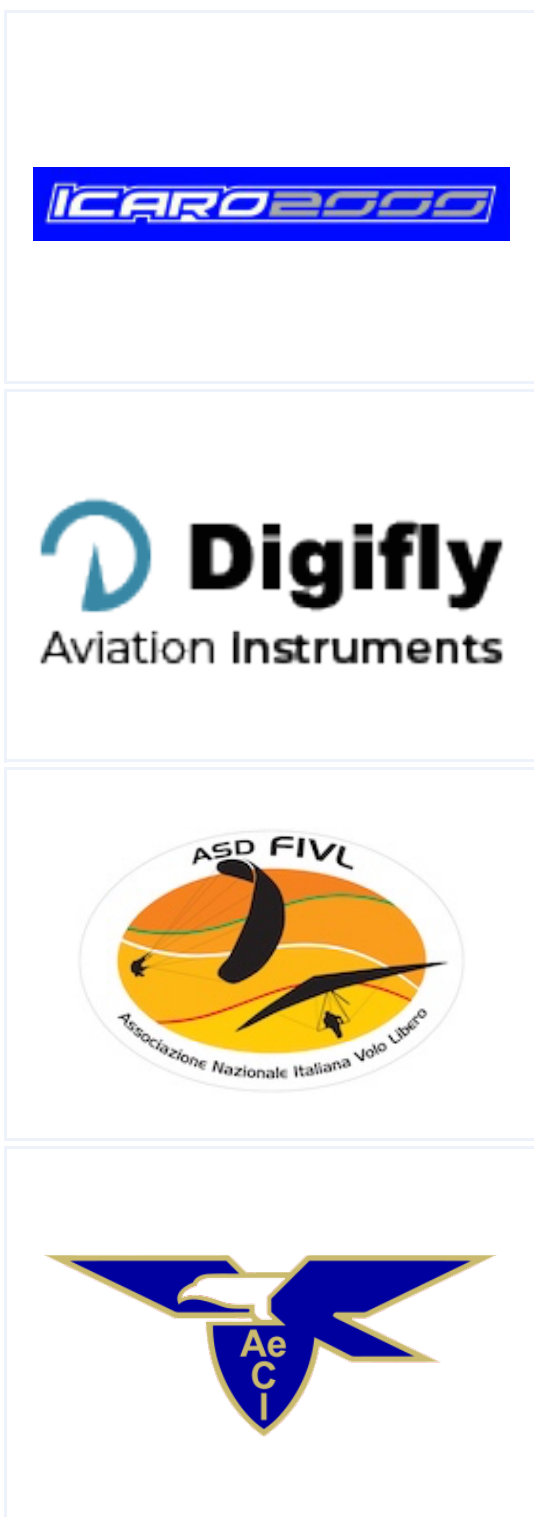
Task statistics

param	value
ss_distance	37.917
task_distance	41.043
launch_to_ess_distance	40.443
no_of_pilots_present	11
no_of_pilots_flying	11
no_of_pilots_lo	10
no_of_pilots_reaching_nom_dist	2
no_of_pilots_reaching_es	1
no_of_pilots_reaching_goal	1
sum_flown_distance	140.582
best_dist	41.043
best_time	1.511944444444444
worst_time	1.511944444444444
no_of_pilots_in_competition	11
no_of_pilots_landed_before_stop	0
sum_dist_over_min	77.182
sum_real_dist_over_min	77.182
best_real_dist	41.043
last_start_time	2026-04-25T15:00:00+02:00
first_start_time	2026-04-25T15:00:16+02:00
first_finish_time	2026-04-25T16:30:43+02:00
max_time_to_get_time_points	0.0
no_of_pilots_with_time_points	1
goalratio	0.090909090909091
arrival_weight	0.03
departure_weight	0
leading_weight	0.042
time_weight	0.166
distance_weight	0.762
smallest_leading_coefficient	1.09337976677621
available_points_distance	322.11012266359256
available_points_time	70.28783299814307
available_points_departure	0
available_points_leading	17.57195824953577
available_points_arrival	12.55139874966841
time_validity	1.0
launch_validity	1.0
distance_validity	0.423
stop_validity	1.0
day_quality	0.423
ftv_day_validity	0.42252131266093984
time_points_stop_correction	0

Scoring formula settings

param	value
id	GAP2025
min_dist	7
nom_dist	30
nom_time	1.5
nom_launch	0.96
nom_goal	0.3
day_quality_override	0
bonus_gr	5
jump_the_gun_factor	2.0
jump_the_gun_max	300
normalize_1000_before_day_quality	0
time_points_if_not_in_goal	0.8
use_1000_points_for_max_day_quality	0
use_arrival_position_points	1
use_arrival_time_points	0
use_departure_points	0
use_difficulty_for_distance_points	1
use_distance_points	1
use_distance_squared_for_LC	0
use_leading_points	1
use_semi_circle_control_zone_for_goal_line	1
use_time_points	1
scoring_altitude	QNH
final_glide_decelerator	none
no_final_glide_decelerator_reason	
min_time_span_for_valid_task	0
score_back_time	15
use_proportional_leading_weight_if_nobody_in_goal	
leading_weight_factor	0.175
turnpoint_radius_tolerance	0.001
use_arrival_altitude_points	0

Sponsors



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