



XXXVIII Valerio Albrizio Trophy 2026

📅 Apr 24 - Apr 26, 2026

🇮🇹 Laveno Mombello, ITA



Category 2
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RESULTS

REGISTRATION



Task3 Overall

2026-04-26

Task info

 Task is set 30.619 km. Start at 14:30. Task deadline at 18:30.

 [Live tracking](#)

Updated Apr 27, 2026 07:49

#	Id	Name	Nat	Glider	Sponsor	SS	ES	Time [h:m:s]	Speed [km/h]	Distance [km]	Dist. Points	Lead. Points	Time Points	Arr. Pos. Points	Total		
1	771	CESARE CRISTOFORONI	M	ITA	Icaro2000 Mastr			14:30:00	6T17:13:	02:43:53	10.29	30.6	244.2		57.0	10.2	311.3
2	773	GARY WIRDNAM	M	GBR	Icaro2000 Alto			14:30:00			19.5	199.9	14.2				214.1
3	777	PAWEŁ WIERZBOWSKI	M	AUT	Vega Mx	Sonnenhof Kadolz		14:30:00			16.9	184.9	0.6				185.5
4	774	MANUEL BALDIN	M	ITA	Willis Wing U2			14:30:00			8.8	126.5					126.5
5	772	FEDERICO ROMANI	M	ITA	Icaro2000 Mastr			14:30:00			8.2	122.4					122.4
6	775	MARIAN KOMAN	M	POL	Willis Wing Sport 3			14:30:00			7.0	111.8					111.8
6	776	MARIO SANSEVERINO	M	ITA	Icaro2000 Alto L	Sanseverinocostruzioni					7.0	111.8					111.8
6	778	PHILIPP REICHEGGER	M	ITA	Willis Wing Sport 3						7.0	111.8					111.8
6	779	SEBASTIAN DALMAU	M	ECU	Icaro2000 Orbiter-2	Bodeguitas Express	14:30:00				7.0	111.8					111.8
6	758	GERD LAUBENTHAL	M	SUI	Designproducts She						7.0	111.8					111.8
ABS	780	SERGE MAINENTE	M	FRA	Willis Wing Sport 3	MyWife- Tahiti Delta Club											0.0

Task definition

No	Leg	Dist.	Id	Radius	Open	Close	Coordinates	Altitude
1		0.0 km	3NU111	0 m	13:45	14:15	Lat: 45.92225, Lon: 8.67407	1110 m
2SS		2524.9 km	SMA109	3000 m	14:30	15:30	Lat: 45.92693, Lon: 8.74498	1090 m
3		5125.6 km	SMA109	400 m	14:30	18:30	Lat: 45.92693, Lon: 8.74498	1090 m
4		12886.1 km	FUN095	400 m	14:30	18:30	Lat: 45.91126, Lon: 8.63699	950 m
5		19532.9 km	SMI106	1000 m	14:30	18:30	Lat: 45.94777, Lon: 8.72022	1060 m
6		21609.5 km	SMA109	400 m	14:30	18:30	Lat: 45.92693, Lon: 8.74498	1090 m
7		30083.1 km	PIC053	400 m	14:30	18:30	Lat: 45.88601, Lon: 8.64346	530 m
8ES		30618.7 km	1AT030	400 m	14:30	18:30	Lat: 45.89688, Lon: 8.63927	300 m
9		30618.7 km	1AT030	400 m	14:30	18:30	Lat: 45.89688, Lon: 8.63927	300 m

Penalties

id	Name	Penalty %	Penalty Points	Penalty Reason
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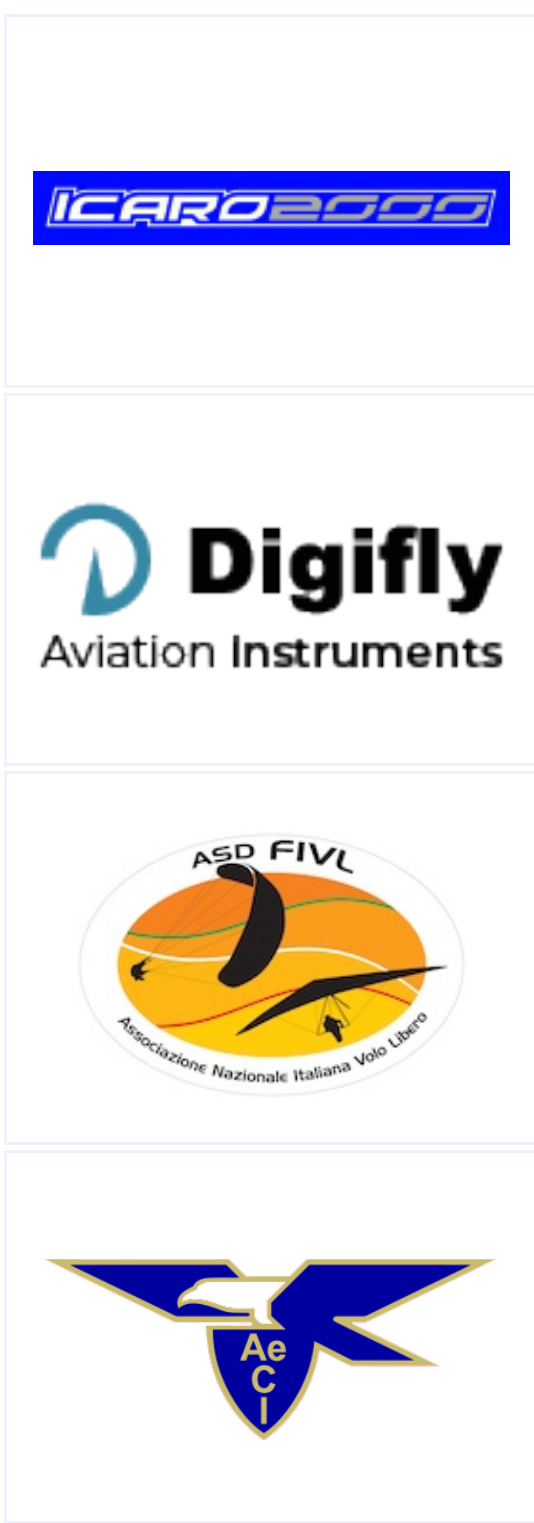
Task statistics

param	value
ss_distance	28.094
task_distance	30.619
launch_to_ess_distance	30.619
no_of_pilots_present	10
no_of_pilots_flying	10
no_of_pilots_lo	9
no_of_pilots_reaching_nom_dist	1
no_of_pilots_reaching_es	1
no_of_pilots_reaching_goal	1
sum_flown_distance	98.691
best_dist	30.619
best_time	2.73138888888889
worst_time	2.73138888888889
no_of_pilots_in_competition	11
no_of_pilots_landed_before_stop	0
sum_dist_over_min	48.967
sum_real_dist_over_min	48.967
best_real_dist	30.619
last_start_time	2026-04-26T14:30:00+02:00
first_start_time	2026-04-26T14:30:03+02:00
first_finish_time	2026-04-26T17:13:53+02:00
max_time_to_get_time_points	0.0
no_of_pilots_with_time_points	1
goalratio	0.1
arrival_weight	0.031
departure_weight	0
leading_weight	0.044
time_weight	0.175
distance_weight	0.75
smallest_leading_coefficient	1.29529839874345
available_points_distance	244.15039087035066
available_points_time	56.95536052672468
available_points_departure	0
available_points_leading	14.23884013168117
available_points_arrival	10.17060009405798
time_validity	1.0
launch_validity	1.0
distance_validity	0.326
stop_validity	1.0
day_quality	0.326
ftv_day_validity	0.3255151916228145
time_points_stop_correction	0

Scoring formula settings

param	value
id	GAP2025
min_dist	7
nom_dist	30
nom_time	1.5
nom_launch	0.96
nom_goal	0.3
day_quality_override	0
bonus_gr	5
jump_the_gun_factor	2.0
jump_the_gun_max	300
normalize_1000_before_day_quality	0
time_points_if_not_in_goal	0.8
use_1000_points_for_max_day_quality	0
use_arrival_position_points	1
use_arrival_time_points	0
use_departure_points	0
use_difficulty_for_distance_points	1
use_distance_points	1
use_distance_squared_for_LC	0
use_leading_points	1
use_semi_circle_control_zone_for_goal_line	1
use_time_points	1
scoring_altitude	QNH
final_glide_decelerator	none
no_final_glide_decelerator_reason	
min_time_span_for_valid_task	0
score_back_time	15
use_proportional_leading_weight_if_nobody_in_goal	
leading_weight_factor	0.175
turnpoint_radius_tolerance	0.001
use_arrival_altitude_points	0

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